

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S32	8	arimatsu-taro.in.	US-PGPUB; USPAT	OR	ON	2005/01/14 14:04
S34	70	watanabe-atsushi.in. and fanuc\$. as.	US-PGPUB; USPAT	OR	ON	2005/01/14 14:06
S35	106	((382/153).CCLS.) and (inspect\$3 or measur\$3 or measurement)	US-PGPUB; USPAT	OR	ON	2005/01/14 14:10
S36	135	(382/153).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2005/01/14 14:16
S37	59	((382/153).CCLS.) and (learn\$3 or teach\$3 or registered or registering or registration)	US-PGPUB; USPAT	OR	ON	2005/01/14 14:26
S38	20	("382"/\$.ccls. "901"/\$.ccls.) and watanabe-atsushi.in.	US-PGPUB; USPAT	OR	ON	2005/01/14 14:29
S39	215	(382/152).CCLS.	US-PGPUB; USPAT; USOCR	OR	OFF	2005/01/14 14:30
S40	45	((382/152).CCLS.) and robot\$3	US-PGPUB; USPAT	OR	ON	2005/01/14 14:42
S41	78	((382/151).CCLS.) and robot\$3	US-PGPUB; USPAT	OR	ON	2005/01/14 14:45
S44	157	((382/151-154).CCLS.) and (recogni\$6 or identif\$3 or identification) same robot\$3	US-PGPUB; USPAT	OR	ON	2005/01/14 15:03
S46	24	((plural\$3 or multiple or dual or two or several or many) adj robot\$3) same (video or camera or CCD or image or visual) same (workpiece or work-piece or work adj (part or piece) or model\$4)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/01/14 15:14
S48	131	((plural\$3 or multiple or dual or two or several or many) adj robot\$3) and (video or camera or CCD or image or visual) same (workpiece or work-piece or work adj (part or piece) or modeled or modeling or modell\$3)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/01/14 15:18
S49	30	robot\$3 same (camera or visual or CCD or optical) same (ax\$s with rotat\$3 with (perpendicular or orthogonal))	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/01/14 15:44

S50	20	((382/154).CCLS.) and (reference or register\$3 or registration or teach\$3 or train\$3 or learn\$3) with (object or model or part or workpiece or work-piece or work adj piece) same robot\$3	US-PGPUB; USPAT	OR	ON	2005/01/14 15:47
S52	76	901/47.ccls. and (workpiece or (work adj piece) or model or part) with (position or location) with (posture or orientation or arrangement or pose or attitude)	US-PGPUB; USPAT	OR	ON	2005/01/14 15:49
S53	1	("6,540,104").PN.	US-PGPUB; USPAT	OR	OFF	2005/01/14 15:51
S54	22	901/47.ccls. and (plural\$3 or multiple or several or many) with (video or camera or CCD or image or visual) same (workpiece or work-piece or work adj (part or piece) or model\$4)	US-PGPUB; USPAT	OR	ON	2005/01/14 16:07
S55	324	(robot with (camera or CCD or image or visual)) same (robot with (workpiece or work-piece or (work adj part or piece) or model))	US-PGPUB; USPAT	OR	ON	2005/01/14 16:12
S56	194	("382"/\$.ccls. "348"/\$.ccls. "356"/\$.ccls. "700"/\$.ccls. "901"/\$.ccls.) and robot\$3 same (camera or CCD or imag\$3 or video) same (position\$3 or locat\$4 or (three or "3") adj dimension\$4 or 3D or 3-D or coordinate) with (orientation or posture or attitude or pose) with (object or workpiece or work adj piece or part or bin or pile\$1 or article or body)	US-PGPUB; USPAT	OR	ON	2005/01/14 16:19
S57	187	(robot\$3 or effector or manipulator) same (camera or CCD or imag\$3 or video or visual) same (orientation or posture or attitude or pose or arrangement) same (compar\$5 or correlat\$4 or collat\$4 or match\$3 or correspond\$4) with (model or stor\$3 or taught or teaching or learn\$3 or reference or registered or registration or recogni\$6 or identif\$4 or template or target)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/01/18 13:10

S58	69	(robot\$3 or effector or manipulator) same (camera or CCD or imag\$3 or video or visual) same (orientation or posture or attitude or pose or arrangement or direction or trajectory) with (associat\$3 or accompan\$4 or together or pair\$3 or link\$3 or affiliat\$3) with (model or stor\$3 or taught or learned or reference or registered or registration or template or target)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/01/18 13:28
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